

TORMAX Technologies, Inc.

TORMAX TTX

Low Energy Swing Door Operator
Installation and Tune-In Manual

TORMAX Technologies, Inc. 121 Interpark Boulevard, Suite 604

San Antonio, TX 78216 Phone: 1-888-685-3707 Phone: 210-494-3551

Fax: 210-494-5930 www.tormaxautomatic.com

TORMAX TTX Low Energy Swing Door Operator

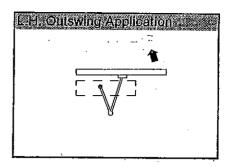
Power Supply 120 VAC Maximum Current 1 A Motor 24 VDC Accessories Output 24VDC 0.3 A Max.

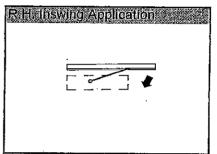
Lock Output 12-24VDC 1.2A Max (power to lock 0.5-0.7S)
Unit Size 5" Wide x 4 9/16" High x 31 1/2" Length

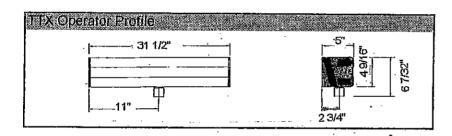
Door Size 220 Lbs. Max.
Door Width 48" Max.

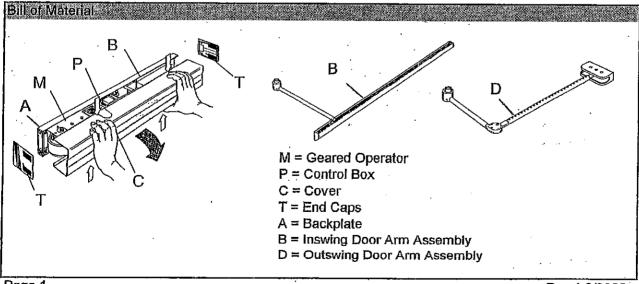
Adjustable Opening Speed 7 Seconds Maximum Adjustable Closing Speed 10 Seconds Maximum Adjustable Hold Open Time 0 - 25 Seconds

Obstruction Time Out 5 Seconds
Opening Torque 9 Lbs. Maximum
Closing Torque 5 Lbs. Maximum
Opening Stop by Mircoswitch

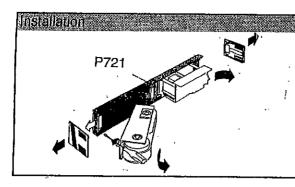






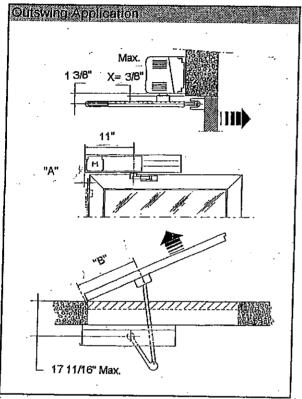


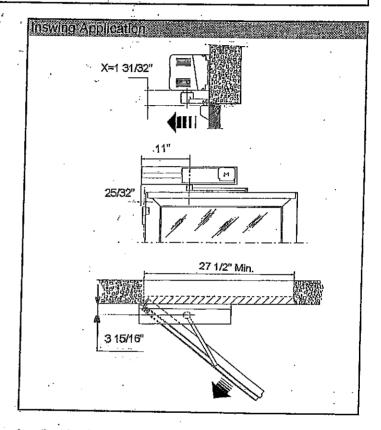
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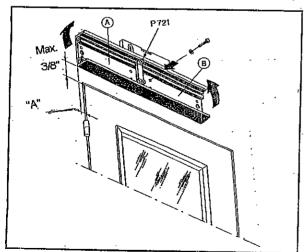


Disconnect the connectors from the PC board and remove the control box and operator from backplate extrusion. Do not remove the P721 clamp and rubber noise suppression material between the geared motor and the aluminum backplate extrusion.

Secure the backplate extrusion to the wall or door frame (refer to dimension "X")







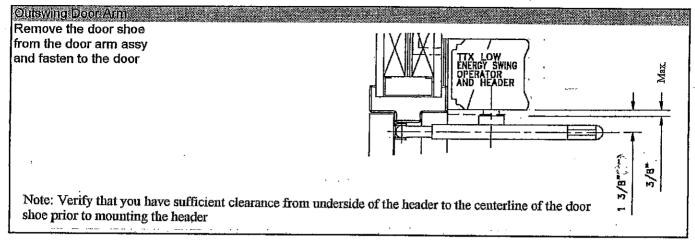
Inswing Applications: Position the operator so that the motor is furthest from the hinges. Position control box on hinge side of operator.

Outswing Applications: Position the operator so that the motor is closest to the hinges. Position control box strike side of operator.

Outswing Application		0-2 Degrees	3-45 Degrees	46-90 Degrees
Distance "A"	Distance	Initial Door Release	Set Door In Motion	Door to Full Open Position
25/32"	13 3/8"	30 lbf.	12 lbf.	8 lbf.
25/32"	149/16"	26 lbf.	14 lbf,	10 lbf.
1 3/4"	14 9/16"	23 lbf.	10 lbf.	8 lbf.

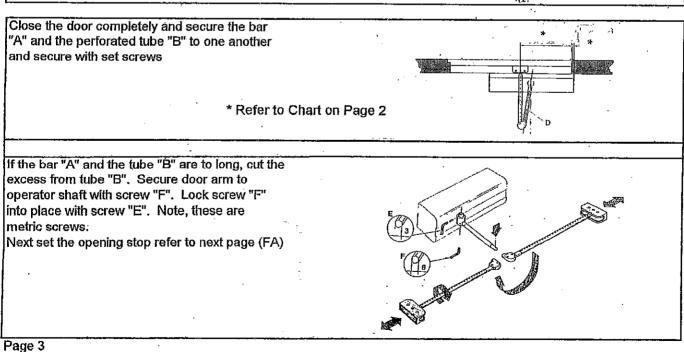
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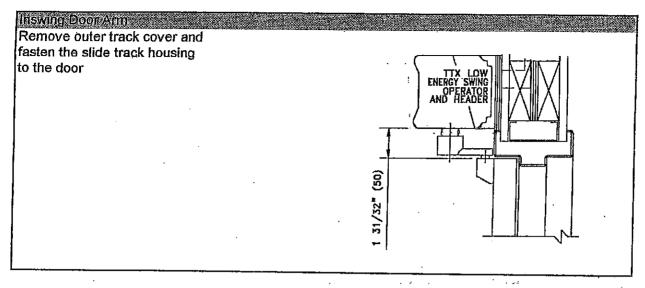
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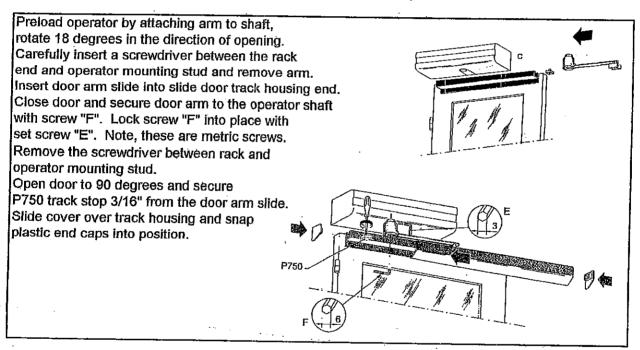
Note: The operator shaft rotation shall not exceed 170 degrees. It is recommended that a mechanical doorstop be utilized as a positive stop with the door in the fully open position. Using the arm extension stop beyond 90 degrees may cause damage to the door arm.

Separate the threaded bar "A" from the perforated tube "B". Secure the treaded bar "A" to the door shoe. Attach the door arm to the operator spindle at 90 degrees. Manually preload the operator in the direction of swing 18 degrees (or equivalent to one operator shaft tooth) and hold in place.

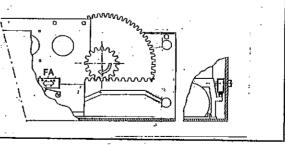




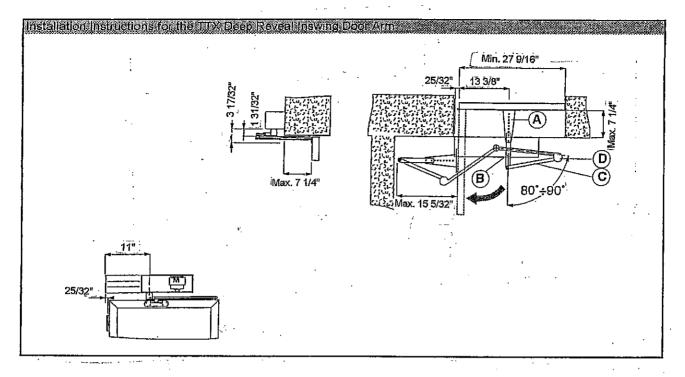
Warning: The operator shaft rotation shall not exceed 170 degrees. When open, the door leaf should rest against the arm extension stop or a mechanical floor door stop.



FA = Opening Stop. Manually open door to desired position, loosen the stop switch screws and position stop switch so that the switch lever engages against the rack in the full open position. Retighten screws.



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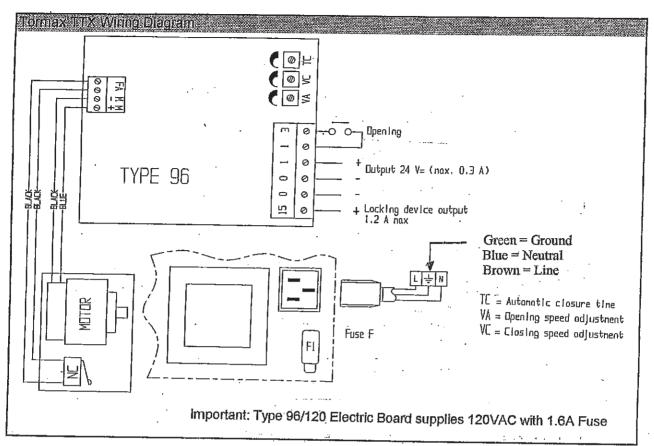


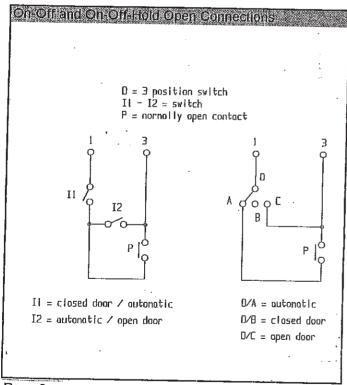
Installation

Adjust the length of arm components "A" + "B" so as to form an angle of between 80 - 90 degrees with respect to arm component "D".

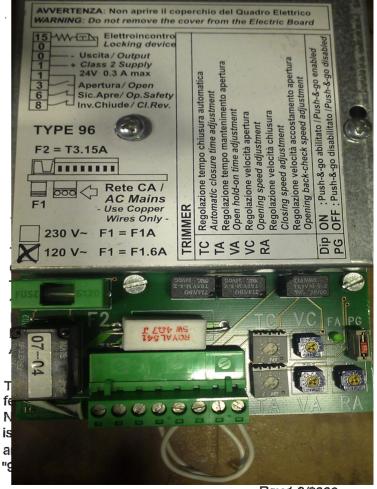
The maximum reveal is 7 1/4" (distance from the face of the door to the back of the operator housing).

The TTX Deep Reveal Inswing Door Arm is configured for a RH Inswing door. For LH inswing door separate arm component "C" from "D" (after having first removed the pin) and reassemble the two arm components rotated 180 degrees.





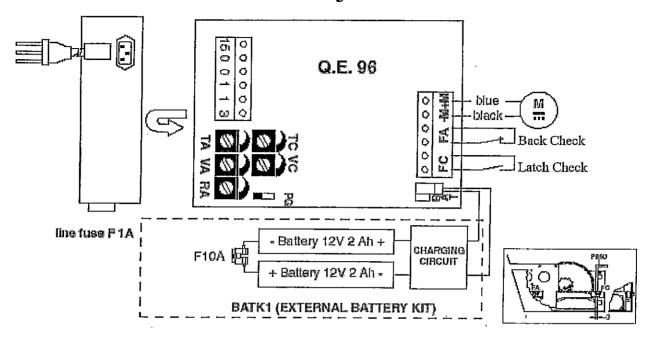
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TTX Tune-In and Adjustment Addendum



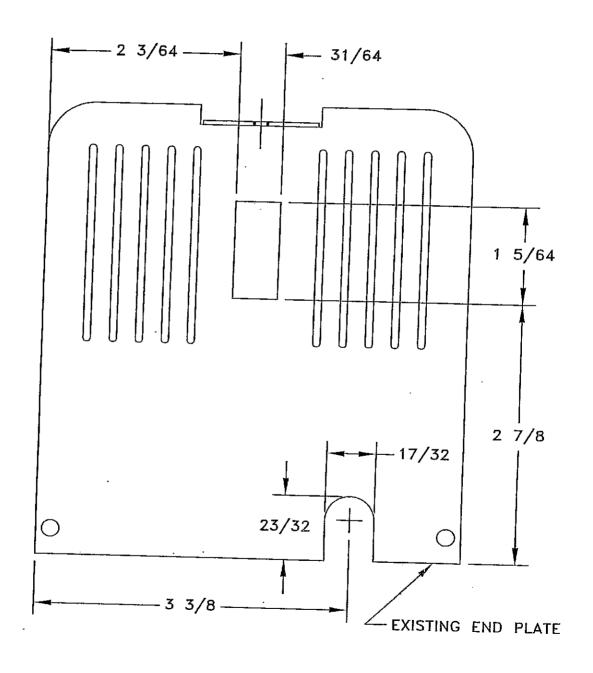
- TC Push Plate Time Delay: Adjusts the hold open time duration (from 0 to 25 s) when the door is activated by a push plate or other type of sensor. The time delay begins when the back check switch (FA) has been tripped.
- TA Push & Go Time Delay: Adjusts the hold open time duration (from 0 to 25 s) when the door is activated by push and go. The time delay begins when the back check switch (FA) has been tripped.
- VA Opening Speed: Adjusts the opening speed.
- VC Closing Speed: Adjusts the closing speed.
- RA Opening Back Check Run Time: Adjusts the opening back check run time when the back check switch (FA) has been tripped. NOTE: An increase or decrease of RA has a direct impact on VA.
- 1. Set position of back check (FA) and latch check (FC) micro switches. (Brass screws on top or bottom of operator depending on outswing or inswing application; see figure above.)
- 2. Set "Push and Go" feature ON or OFF. The switch is located next to potentiometer RA.
- 3. Set RA pot at 3/4 rotation and set all other potentiometers at 1/2 rotation before activating door.
- 4. Activate door.
- 5. Adjust VA and VC to the desired opening and closing speeds respectively.
- 6. Readjust RA to the desired door opening angle. Note: Increasing or decreasing RA will have a direct impact on opening velocity. VA may have to be readjusted for desired results.
- 7. Set TC to the desired push and go time delay.
- 8. Set TA to the desired push plate time delay. (Push Plate Time Delay = TC + TA)



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PLATE MACHINING END

JOB NAME: _DATE:_ DOOR LOCATION: DOOR NO:__ SHEET_ OF



NOTES:

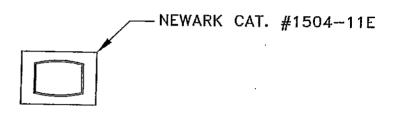
1. DETAILS NOT TO SCALE
2. FILE SLOT CORNERS SQUARE FOR ROCKER SWITCH
3. MACHINE SLOT FOR POWER CORD (REV. B)
4. MOUNT THIS END PLATE ON CONTROL BOX END OF BACK PLATE

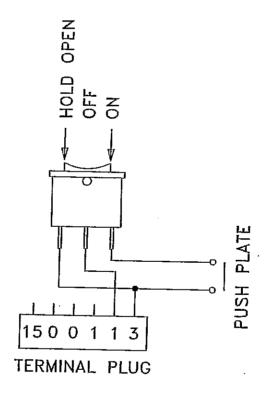


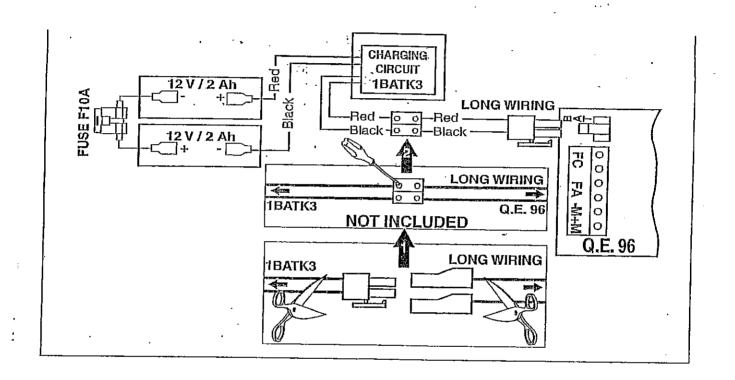
TTX SERIES

END PLATE W/ ROCKER SWITCH WIRING

JOB NAME: _____ DATE: _____
DOOR LOCATION: _____ DOOR NO: ____ SHEET __OF ___







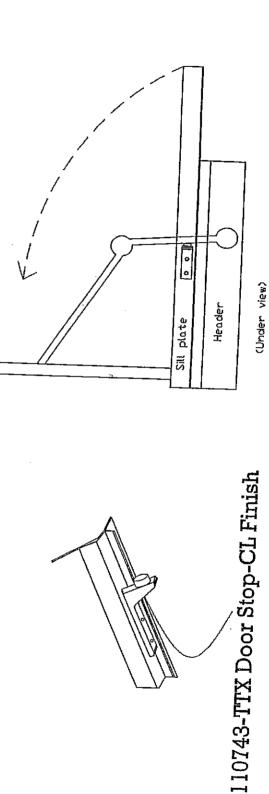
DOOR ARM BRKT



Installation of Door Arm Stop

Instructions

- l. Install TTX Door Arm Stop to the horizontal sill. Position between hing & operator spindle with rubber stop facing door arm.
- 2. Adjust door arm stop to desired door opening position
- 3. Fasten door arm stop with appropriate fasteners using bracket holes as a guide



Header

